

Energy-efficient timetabling for mixed train flow. ELBRUS Automated Systems

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Mission of ELBRUS Family Automated Systems

Objective

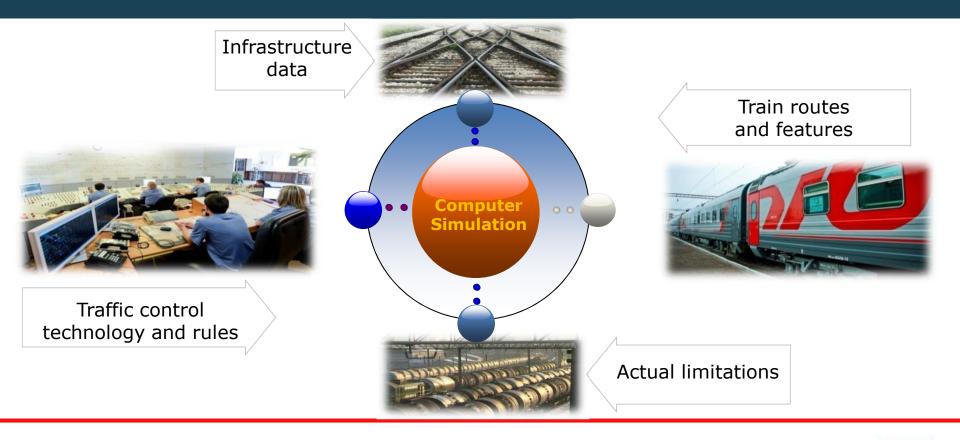
Electric energy saving for train traction

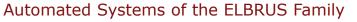
<u>Methods</u>

- **1.APC ELBRUS** System: Energy-efficient train timetabling for short time planning (scope 1-14 days)
- **2.ELBRUS-OPP** System: Energy-efficient train timetabling for dynamic planning (scope 2-6 hours)
- **3.ELBRUS-EOS** System: Optimal train velocity and traction power control calculation



Core of the ELBRUS Computer-Based Simulation Model





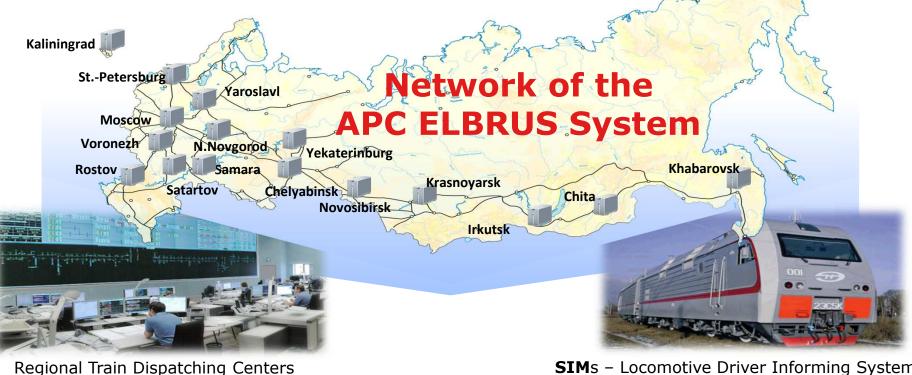
DX

APC ELBRUS Operational Area: from Far East to Europe Route





Cluster Network of the APS ELBRUS System over Russian Railways

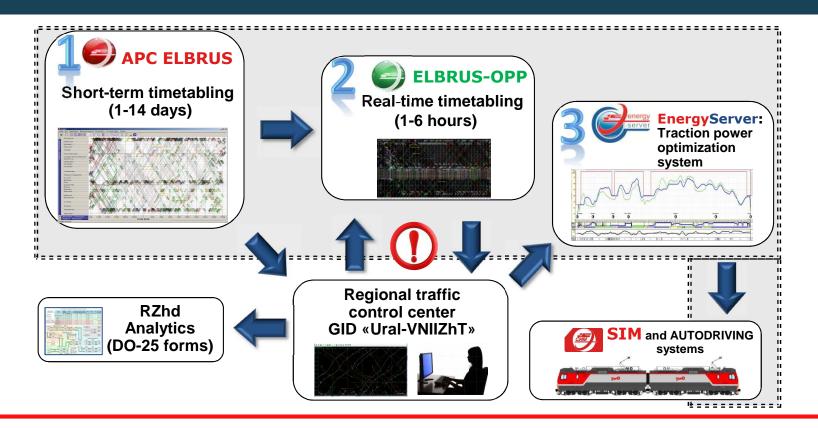


SIMs – Locomotive Driver Informing Systems



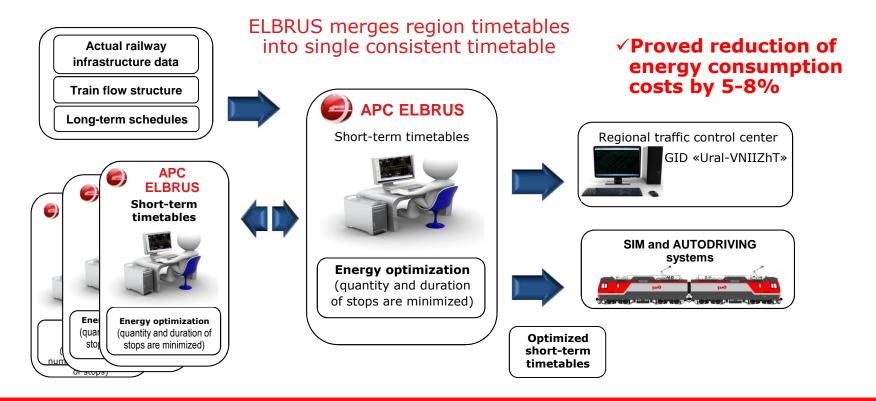
Automated Systems of the ELBRUS Family

Automatic Train Schedule Management Systems of the ELBRUS Family



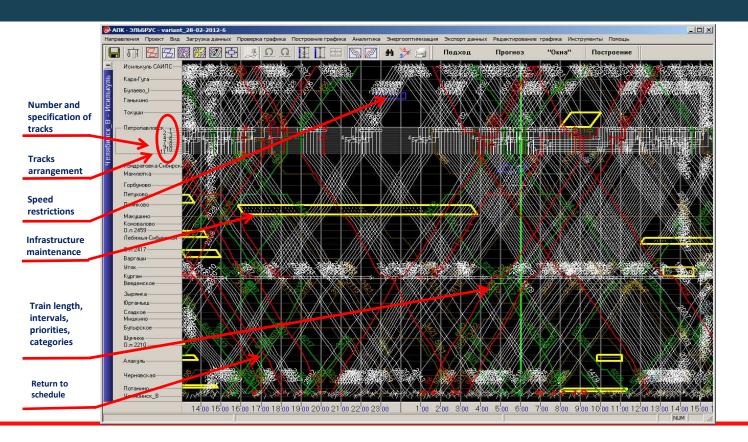


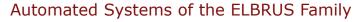
APC ELBRUS: Technology of the Energy-efficient Short-term Timetabling





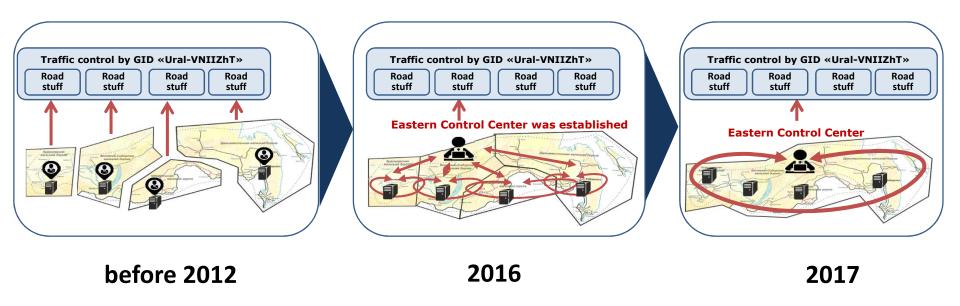
APC ELBRUS Operation Mode: Short-Term Timetabling





APC ELBRUS Evolution After Eastern Control Center of Russian Railways was Established

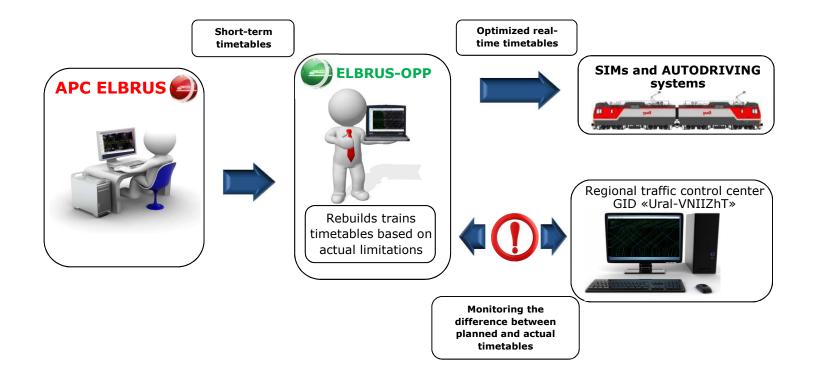
Eastern Control Center of Russian Railways now is responsible for **11876 km** of railways over 4 divisions of RZhD

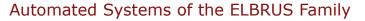




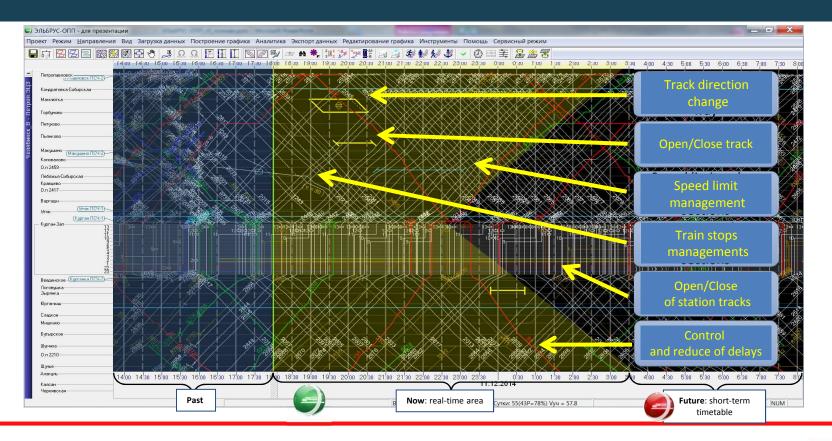
Automated Systems of the ELBRUS Family

ELBRUS OPP: Real-time Energy-Efficient Timetabling Technology





ELBRUS OPP: Real-time Energy-Efficient Timetabling



EnergyServer: Fine-Grained Traction Power Optimization System

Objective

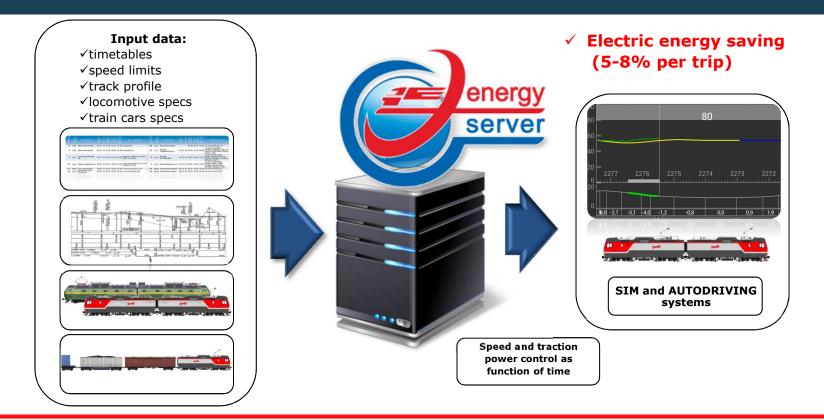
Optimal train velocity and traction power control calculation

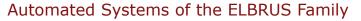


Methods

- Optimal traction power control calculation service
- Unified way to bring energy optimization functionality to different automated systems ("Energy Optimization Factory")

EnergyServer: How Energy Optimization Factory Works





DX

EnergyServer: Mathematical Model of Energy Optimization

Traveling time determination by common train path (TP)

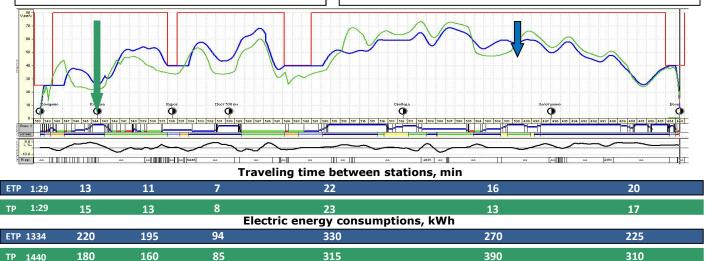
$$m \frac{dv(t)}{dt} = F_{T}(t) - B(t) - W_{n} \qquad \text{If} \quad V(t_{o}) = V_{o}$$

Train velocity – V(t) locomotive power – FT, speed train resistance – Wn and conditions, train velocity at the beginning - Vo

Traveling time determination by means of energy optimal train path (ETP)

$$\begin{split} m \, \frac{dv(t)}{dt} &= F_{_{T}}\left(t\right)_{_{T_{_{K}}}} B(t) - W_{_{n}} \qquad \text{If } V(t_{_{o}}) \;=\; V_{_{o}} \, \text{and} \, V(t_{_{\kappa}}) \;=\; V_{_{\kappa}} \\ \text{and also } A &= \int F(t) \cdot V(t) dt \; \Rightarrow \; \min \end{split}$$

The solution of differential system of ETP equations reflects both the restrictions to infrastructure parameters, and providing minimum consumptions of energy





SIM: Locomotive Driver Information Systems

Usage in the automatic train driving systems:

- \checkmark timetable
- ✓ track profile
- ✓ traction power modes and velocity
- ✓ locomotive cab data



Usage for mobile devices:

energy-optimal velocity

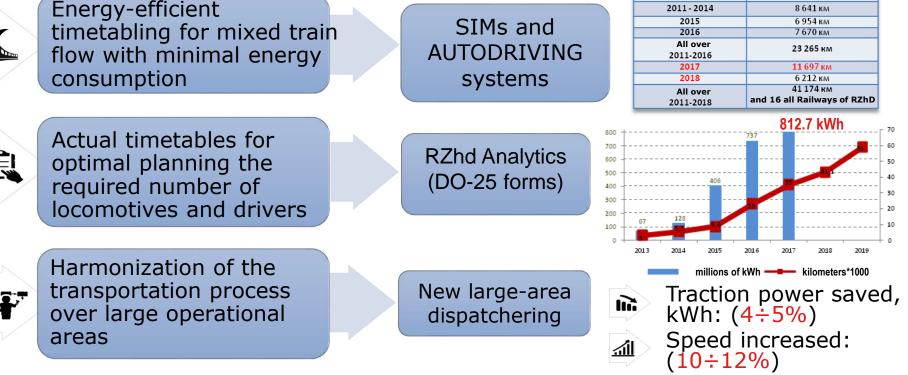
- \checkmark timetable
- ✓ track profile





ELBRUS Systems Energy Efficiency Over 2011-2018







Years

APC ELBRUS works at



-

APC ELBRUS Summary

1-st Prize of UIC in 2012:

APC ELBRUS works over 42 000 km of Russian Railways

Russian Railways saved 812.7 millions of kWh in 2017



Thank you for your attention and time!

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